

Algorithme d'optimisation polynomiale en utilisant de bases de bord

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Our Problem

$$f^* = \inf_{\mathbf{x} \in \mathcal{S}} f(\mathbf{x})$$

where $\mathcal{S} = \{\mathbf{x} \in \mathbb{R}^n \mid g_1^0(\mathbf{x}) = \dots = g_{n_1}^0(\mathbf{x}) = 0, g_1^+(\mathbf{x}) \geq 0, \dots, g_{n_2}^+(\mathbf{x}) \geq 0\}$

and $V_{min} = \{\mathbf{x}^* \in \mathcal{S} \text{ s.t. } f(\mathbf{x}^*) = f^*\}$

Moment problem

$$f^* = \inf_{\mathbf{x} \in \mathcal{S}} f(\mathbf{x})$$

$$\text{where } f(\mathbf{x}) = \sum f_{\alpha} \mathbf{x}^{\alpha}$$

$$f^* = \inf_{\mu} \int_{\mathcal{S}} f(\mathbf{x}) \mu(dx) = \inf_{\mu} \sum f_{\alpha} \int_{\mathcal{S}} \mathbf{x}^{\alpha} \mu(dx) \text{ where } \int_{\mathcal{S}} \mathbf{x}^{\alpha} \mu(dx) = \mathbf{y}_{\alpha}$$

$$f^* = \inf f^T \mathbf{y} \text{ s.t } \mathbf{y}_0 = 1, \mathbf{y} \text{ has a representating measure on } \mathcal{S}$$

Lasserre Full moment relaxation

$$f_G^\mu = \inf \Lambda(f) \text{ s.t. } \Lambda(1) = 1, \Lambda(p) \geq 0 \ \forall p \in \overbrace{\sum_{g \in G^0} g h + \sum_{g' \in \prod G^+} g' h'}^{\mathcal{P}_G} \text{ with } h \in \mathbb{R}[\mathbf{x}], h' \text{ is sos.}$$

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IDEA-Truncated convex problems relaxation

$$f_{t,G}^\mu = \inf \{ \Lambda(f) \text{ s.t. } \Lambda \in \mathbb{R}[\mathbf{x}]_{2t}^*, \Lambda(1) = 1, \Lambda(p) \geq 0, \forall p \in \mathcal{P}_{t,G} \}$$

where

$$\mathcal{P}_{t,G} = \left\{ \sum_{i=1}^{n_1} h g_i^0 + \sum_{\nu \in \{0,1\}^m} h' g_1^+(\mathbf{x})^{\nu_1} \dots g_{n_2}^+(\mathbf{x})^{\nu_{n_2}} \mid h' \text{ sos degree } t - \left\lceil \frac{\prod g_i^+}{2} \right\rceil, h \in \mathbb{R}[\mathbf{x}]_{2t - \deg(g_i^0)} \right\}$$

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$$\dots f_{t,G}^\mu \leq f_{t+1,G}^\mu \leq \dots \leq f^*$$

Why a new algorithm using border basis?

Issues of Lasserre relaxation:

The size and number of parameters in each problem become unhandled when t grows.

Using border basis

- We reduce the size and number of parameters of each problem.
- Sometimes we find the minimum at a lower degree.

We take B a monomial set **connected to 1** and we define $B^+ = B \cup x_1 B \cup \dots \cup x_n B$ and $\partial B = B^+ \setminus B$.

Definition

$F \subset \mathbb{R}[\mathbf{x}]$ is a **border basis** for B in degree $t \in \mathbb{N}$, if

- $\forall m \in \partial B \cap \mathbb{R}[\mathbf{x}]_t, \exists f \in F_t$ s.t. $f = m + \sum_{b \in B_t} c_i b$
- $\mathbb{R}[\mathbf{x}]_t = \langle B \rangle_t \oplus \langle F|t \rangle$

Definition

We define $\pi_{B_t, F_{2t}}$ the **projection** of $\mathbb{R}[\mathbf{x}]_{2t}$ on $\langle B_t \rangle$ along $\langle F|2t \rangle$.

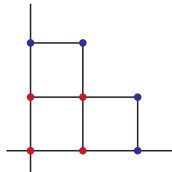
Border basis: example

$$B = \{1, x, y, xy\},$$

$$B^+ = B \cup xB \cup yB = \\ \{1, x, y, xy, x^2, x^2y, xy^2, y^2\},$$

$$\partial B = B^+ \setminus B = \{x^2, x^2y, xy^2, y^2\}$$

$$F_2 = \{x^2 - 1, y^2 - 1\}$$



Border basis hierarchy

- F_{2t} border basis of g^0 for B in degree $2t$,
- $G_t^0 = \{p - \pi_{B_t, F_{2t}}(p), p \in B_t \cdot B_t\}$
- $G_t^+ = \pi_{B_t, F_{2t}}(\mathbf{g}^+)$.

Proposition

$$\dots \leq f_{B_t, G_t}^\mu \leq f_{B_{t+1}, G_{t+1}}^\mu \leq \dots \leq f^*$$

Truncated Hankel operators and Optimal linear form

Definition

- Let $E \subset \mathbb{R}[\mathbf{x}]$ be a vector space and let $\Lambda \in \langle E \cdot E \rangle^*$ be a linear form,

$$\begin{aligned} H_{\Lambda}^E : E &\longrightarrow E^* \\ p &\longmapsto p \cdot \Lambda = \Lambda(pq) \quad \forall q \in E \end{aligned}$$

is a *truncated Hankel operator*.

- $\ker H_{\Lambda}^E = \{p \in E \mid p \cdot \Lambda = 0, \text{ i.e., } \Lambda(pq) = 0 \quad \forall q \in E\}$
- The matrix of this operator H_{Λ}^E is the **Moment Matrix**: $[H_{\Lambda}^E] = (\Lambda(\mathbf{x}^{\alpha+\beta}))_{\mathbf{x}^{\alpha} \in E, \mathbf{x}^{\beta} \in E}$

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$$\mathcal{L}_{E,G} = \{\Lambda \in \langle E \cdot E \rangle^*, \Lambda(1) = 1, \Lambda(p) \geq 0, \forall p \in \mathcal{P}_{E,G}\}$$

Definition

$\Lambda^* \in \mathcal{L}_{E,G}$ is *optimal linear form for f* if $\text{rank } H_{\Lambda^*}^E = \max_{\Lambda \in \mathcal{L}_{E,G}, \Lambda(f)=f_{E,G}^{\mu}} \text{rank } H_{\Lambda}^E$.

Theorem

Let our polynomial f and the set $\mathcal{S}$ and let $G \subset \mathbb{R}[\mathbf{x}]$ be a set of constraints defined as our border basis relaxation. There exist $t_1 \in \mathbb{N}$ such that $\forall t \geq t_1$

- $f_{t,G}^\mu = f^*$ is reached for some $\Lambda^* \in \mathcal{L}_{t,G}$*
- $\forall \Lambda^* \in \mathcal{L}_{t,G}$ optimal for f , $\Lambda^*(f) = f^*$ and $\ker H_{\Lambda^*}^t = I_{\min}$.*

How to find $\Lambda^* \in \mathcal{L}_{E,G}$ optimal linear form for f ?

Optimal linear form Algorithm- SemiDefinite Programming

Input: $f \in \mathbb{R}[\mathbf{x}]$, $B_t = (\mathbf{x}^\alpha)_{\alpha \in A}$ a monomial set containing 1 with $f \in \langle B_t \cdot B_t \rangle$, $G \subset \mathbb{R}[\mathbf{x}]$.

- SDP problem: $\text{argmin}_\Lambda \Lambda(f)$ s.t.
 - ① $H_{\Lambda^*}^{B_t} = (\Lambda^*(\mathbf{x}^{\alpha+\beta}))_{\alpha, \beta \in A} \succcurlyeq 0$, and $\Lambda^*(1) = 1$
 - ② $H_{g^+ \cdot \Lambda^*}^{B_t - w} \succcurlyeq 0$ for all $g^+ \in G^+$ where $w = \lceil \frac{\deg(g^+)}{2} \rceil$.
 - ③ $\Lambda^*(g^0) = 0 \ \forall g^0 \in G^0 \cap \langle B_t \cdot B_t \rangle$.

Output: the minimum $f_{t,G}^\mu$ of f and $\Lambda^* \in \langle B_t \cdot B_t \rangle^*$.

👉 Tools for solving this SemiDefinite Programming problem: SDPA, MOSEK,...

Example for $t = 3$:

Minimize $x^2 + 3$ s.t. $g = x^4 - x^3 - x + 1 = (x - 1)^2(x^2 + x + 1) = 0$.

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$$F_3 = \{x^4 - x^3 - x + 1\}, \quad B_3 = \{1, x, x^2, x^3\}, \quad G_3^0 = \{\underline{x^4} - x^3 - x + 1, \underline{x^5} - x^3 - x^2 + 1, \underline{x^6} - 2x^3 + 1\}$$

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Minimize $\Lambda(x^2 + 3) = \Lambda(x^2) + 3$

with Λ s.t.

$$\Lambda(1) = 1,$$

$$\Lambda(x^4) = \Lambda(x^3) + \Lambda(x) - \Lambda(1),$$

$$\Lambda(x^5) = \Lambda(x^3) + \Lambda(x^2) - \Lambda(1),$$

$$\Lambda(x^6) = 2\Lambda(x^3) - \Lambda(1)$$

and

$$H_\Lambda^3 := \begin{pmatrix} 1 & a & b & c \\ a & b & c & c + a - 1 \\ b & c & c + a - 1 & c + b - 1 \\ c & c + a - 1 & c + b - 1 & 2c - 1 \end{pmatrix} \succcurlyeq 0$$

where $a = \Lambda(x)$, $b = \Lambda(x^2)$, $c = \Lambda(x^3)$.

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where $a = \Lambda(x)$, $b = \Lambda(x^2)$, $c = \Lambda(x^3)$.

Solution: $\Lambda^*(1) = 1$, $\Lambda^*(x) = 1$, $\Lambda^*(x^2) = 1$, $\Lambda^*(x^3) = 1$... and the minimum is

$$\Lambda(x^2 + 3) = \Lambda(x^2) + 3 = 4.$$

$$\ker H_{\Lambda^*} = \langle x - 1, x^2 - x, x^3 - x^2 \rangle.$$

How to detect when the minimum is reached? ($\Lambda^*(f) = f^*$)

(Curto-Fialkov 96) If $H_\Lambda^E \succcurlyeq 0$ and $\text{rank } H_\Lambda^E = r$ then

$$\Lambda = \sum_{i=1}^r \omega_i \mathbf{1}_{\xi_i}, \quad \xi_i \in V(\ker H_\Lambda^E)$$

Theorem - Convergence Certification

Let $B \subset E \subset \mathbb{R}[\mathbf{x}]$ be finite dimensional vector spaces connected to 1 with

- $B^+ \subset E$,
- $G^0 \cdot B \subset \langle E \cdot E \rangle$,
- $G^+ \cdot B \cdot B \subset \langle E \cdot E \rangle$.

Let $\Lambda \in \mathcal{L}_{E,G}$ with $\boxed{\text{rank } H_\Lambda^E = \text{rank } H_\Lambda^B = \dim B}$. Then

- 1 $\exists \tilde{\Lambda} \in \mathbb{R}[\mathbf{x}]^*$ which extends Λ ,
- 2 $\tilde{\Lambda} = \sum_{i=1}^r \omega_i \mathbf{1}_{\xi_i}$ with $\omega_i > 0, \xi_i \in \mathcal{S}(G)$,
- 3 $(\ker H_\Lambda^E) = I(\xi_1, \dots, \xi_r)$.

How to check this flat extension property?

Flat extension Algorithm

Input: a vector space E connected to 1 and a linear form $\Lambda^* \in \langle E \cdot E \rangle^*$ and the inner product $\langle p, q \rangle_* := \Lambda^*(pq)$.

- 1 Take $B_0 := \{1\}$, $i = 0$;
- 2 While $B_i^+ \subset E$ or $L_i \neq \{0\}$
 - compute L_i of maximal dim. in B_i^+
 - $\langle L_i, B_i \rangle_* = 0$
 - $L_i \cap \ker H_{\Lambda^*}^{B_i^+} = \{0\}$.
 - $B_{i+1} = B_i + L_i$, $i = i + 1$.
- 3 If $B_i^+ \not\subset E \Rightarrow$ failed
else $L_i = \{0\}$ and $B_i^+ = B_i \oplus \ker H_{\Lambda^*}^{B_i^+} \Rightarrow$ success.

Output: *failed* or *success* with

- a basis $B = \{b_1, \dots, b_r\} \subset \mathbb{R}[\mathbf{x}]$;
- the relations $x_k b_j - \sum_{i=1}^r \frac{\langle x_k b_j, b_i \rangle_*}{\langle b_i, b_i \rangle_*} b_i$, $j = 1 \dots r$ $k = 1 \dots n$.

Flat extension Algorithm: Example

$$\min f(x) = (x - 1)^2 \cdot (x - 2)^2 \cdot (x^2 + 1) + (y - 1)^2 \cdot (y^2 + 1)$$

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We compute the optimal linear form (SDP with $t=3$) and we obtain:

$$\Lambda^*(1) = 1, \Lambda^*(x) = 1.5, \Lambda^*(y) = 1, \Lambda^*(x^2) = 2.5, \Lambda^*(xy) = 1.5, \Lambda^*(y^2) = 1, \Lambda^*(y^3) = 1, \Lambda^*(xy^2) = 1.5, \Lambda^*(x^2y) = 2.5, \Lambda^*(x^3) = 4.5, \Lambda^*(y^4) = 1, \Lambda^*(xy^3) = 1.5, \Lambda^*(x^2y^2) = 2.5, \Lambda^*(x^3y) = 4.5, \Lambda^*(x^4) = 8.5, \dots$$

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$$\bullet B_0 = \{1\}, \partial B_0 = \{x, y\}, B_0^+ = \{1, x, y\}$$

$$H_{\Lambda}^{B_0^+} = \begin{pmatrix} 1 & 1.5 & 1 \\ 1.5 & 2.5 & 1.5 \\ 1 & 1.5 & 1 \end{pmatrix} \longrightarrow H_{\Lambda}^{\{1, x-1.5, y-1\}} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0.25 & 0 \\ 0 & 0 & 0 \end{pmatrix} \longrightarrow \text{rank } H_{\Lambda}^{B_0^+} = 2,$$

Flat extension Algorithm: Example

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$$\bullet B_1 = B_0 + L_0 = \{1, x-1.5\}, \partial B_1 = \{y, x^2-1.5x, xy-1.5y\}, B_1^+ = \{1, x-1.5, y, x^2-1.5x, xy-1.5y\}$$

$$H_{\Lambda}^{B_1^+} = \begin{pmatrix} 1 & 0 & 1 & 0.25 & 0 \\ 0 & 0.25 & 0 & 0.375 & 0.25 \\ 1 & 0 & 1 & 0.25 & 0 \\ 0.25 & 0.375 & 0.25 & 0.625 & 0.375 \\ 0 & 0.25 & 0 & 0.375 & 0.25 \end{pmatrix} \longrightarrow H_{\Lambda}^{\tilde{B}} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0.25 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\text{where } \tilde{B} = \{1, x-1.5, y-1, x^2-3x+2, xy-1.5y-x+1.5\}$$

$$\longrightarrow \text{rank } H_{\Lambda}^{B_1^+} = 2, L_1 = \{0\},$$

Flat extension Algorithm: Example

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$$\bullet B_0 = \{1\}, \partial B_0 = \{x, y\}, B_0^+ = \{1, x, y\}$$

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$$\text{where } \tilde{B} = \{1, x-1.5, y-1, x^2-3x+2, xy-1.5y-x+1.5\}$$

$$\longrightarrow \text{rank } H_{\Lambda}^{B_1^+} = 2, L_1 = \{0\},$$

$$\text{Ker } H_{\Lambda}^{B_1^+} = \{y-1, x^2-3x+2, xy-1.5y-x+1.5\}.$$

How to compute minimizers points?

Minimizer points Algorithm

Multiplication operators: $M_k : a \in \mathcal{A}_{min} \mapsto x_k a \in \mathcal{A}_{min} \quad k = 1, \dots, n$ where $\mathcal{A}_{min} = \mathbb{R}[\mathbf{x}]/I_{min}$ and $I_{min} = \mathcal{I}(\xi_1, \dots, \xi_r) = \langle x_k b_j - \sum_{i=1}^r \frac{\Lambda^*(x_k b_j b_i)}{\Lambda^*(b_i b_i)} b_i \rangle_{j=1 \dots r, k=1 \dots n}$.

Input: $B = \{b_1, \dots, b_r\}$ basis of $\mathcal{A}_{min}$ and $x_k b_j \equiv \sum_{i=1}^r \frac{\Lambda^*(x_k b_j b_i)}{\Lambda^*(b_i b_i)} b_i \mod I_{min}$

- Compute the matrices of the operator M_k in the basis B : $[M_k] = (\frac{\Lambda^*(x_k b_i b_j)}{\Lambda^*(b_i b_i)})_{1 \leq i, j \leq r}$.
- For a generic choice of $l_1, \dots, l_n \in \mathbb{R}$, compute the eigenvectors $\mathbf{u}_1, \dots, \mathbf{u}_r$ of $l_1[M_1] + \dots + l_n[M_n]$.
- Compute $\xi_{i,k} \in \mathbb{R}$ such that $M_k \mathbf{u}_i = \xi_{i,k} \mathbf{u}_i$.

Output: the minimizers $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n})$, $i = 1 \dots r$.

Minimizer points Algorithm: Example

$$M_x^{B=\{1, x-1.5\}} = \begin{pmatrix} 1.5 & 0.25 \\ 1 & 1.5 \end{pmatrix} \longrightarrow \begin{cases} x = 1.5 \cdot 1 + 1 \cdot (x - 1.5) \\ x(x - 1.5) = 0.25 \cdot 1 + 1.5 \cdot (x - 1.5) \end{cases}$$

$$M_y^{B=\{1, x-1.5\}} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \longrightarrow \begin{cases} y = 1 \cdot 1 + 0 \cdot (x - 1.5) \\ y(x - 1.5) = 0 \cdot 1 + 1 \cdot (x - 1.5) \end{cases}$$

$$M = M_x^B + M_y^B = \begin{pmatrix} 2.5 & 0.25 \\ 1 & 1.5 \end{pmatrix} \longrightarrow \lambda_1 = 2, \lambda_2 = 3$$

$$M \cdot u_1 = \lambda_1 \cdot u_1 \rightarrow u_1^T = (-0.5, 1); \quad M \cdot u_2 = \lambda_2 \cdot u_2 \rightarrow u_2^T = (0.5, 1)$$

$$M_x^B \cdot u_1^T = x_1 \cdot u_1^T \rightarrow x_1 = 1; \quad M_x^B \cdot u_2^T = x_2 \cdot u_2^T \rightarrow x_2 = 2$$

$$M_y^B \cdot u_1^T = y_1 \cdot u_1^T \rightarrow y_1 = 1; \quad M_y^B \cdot u_2^T = y_2 \cdot u_2^T \rightarrow y_2 = 1$$

The minimizers points are (1, 1) and (2, 1).

Minimizer Border Basis Algorithm

Input: A real polynomial function f and a set of constraints $\mathbf{g} \subset \mathbb{R}[\mathbf{x}]$ with $V_{\min}$ non-empty finite.

- 1 $t = \max(\lceil \frac{\deg(f)}{2} \rceil, d^0, d^+)$ where $d^0 = \max_{\mathbf{g}^0 \in \mathbf{g}^0}(\lceil \frac{\deg(\mathbf{g}^0)}{2} \rceil)$, $d^+ = \max_{\mathbf{g}^+ \in \mathbf{g}^+}(\lceil \frac{\deg(\mathbf{g}^+)}{2} \rceil)$
- 2 Compute the graded border basis F_{2t} of $\mathbf{g}^0$ for B in degree $2t$.
- 3 Let B_t be the set of monomials in B of degree $\leq t$.
- 4 Let G_t be the set of constraints such that $G_t^0 = \{m - \pi_{B_t, F_{2t}}(m), m \in B_t \cdot B_t\}$ and $G_t^+ = \pi_{B_t, F_{2t}}(\mathbf{g}^+)$
- 5 $[f_{G_t, B_t}^*, \Lambda^*] := \text{OPTIMAL LINEAR FORM}(f, B_t, G_t)$.
- 6 $[c, B', K] := \text{FLAT EXTENSION}(\Lambda^*, B_t)$
- 7 if $c = \text{fails}$ then go to step 2
else with $t := t + 1$. $c = \text{success}$ then $V = \text{MINIMIZER POINTS}(B', K)$

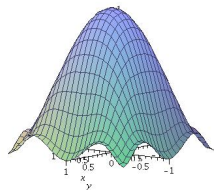
Output: the minimum $f^* = f_{G_t, B_t}^*$, the minimizers $V_{\min} = V$, $I_{\min} = (K)$.

Example - Robinson polynomial

$$f(x, y) = 1 + x^6 - x^4 - x^2 + y^6 - y^4 - y^2 - x^4y^2 - x^2y^4 + 3x^2y^2;$$

$$\nabla f = (6x^5 - 4x^3 - 2x - 4x^3y^2 - 2xy^4 + 6xy^2, 6y^5 - 4y^3 - 2y - 4y^3x^2 - 2yx^4 + 6yx^2)$$

Iteration	Degree	Size	Parameters	$\min \Lambda(f)$	Flat extension
1	3	10	21(28)	-0.93	failed
2	4	15	21(45)	0	success



We obtain:

- $f^* = 0$;
- $I_{min} = (x^3 - x, y^3 - y, x^2y^2 - x^2 - y^2 + 1)$
- $B = \{1, x, y, x^2, xy, y^2, x^2y, xy^2\}$
- $V_{min} = \{(1, 1), (1, -1), (-1, 1), (-1, -1), (1, 0), (-1, 0), (0, 1), (0, -1)\}$

Note: Gloptipoly must go to degree $t = 7$ to find the minimum.

Implementation and comparasion with Gloptipoly

- Implementation

- This algorithm is implemented in the package BORDERBASIX of MATHEMAGIX software.
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- If there are equality constraints the size of the moments matrices and the number of parameters in our method is smaller due to the use of border basis.
- In the other case the Decomposition Algorithm and Minimizer points algorithm are more efficient and quicker than the reconstruction algorithm of Gloptipoly.

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Experimentations

v	c	d	so	t_{bbr}	o_{bbr}	p_{bbr}	s_{bbr}	$t_{bbr+msk}$	t_{fmr}	o_{fmr}	p_{fmr}	s_{fmr}
2	0	6	8	0.15	4	21	15	0.08	*	119	36	
2	0	6	4	0.17	4	26	15	0.12	*	9	189	55
3	1	6	1	3.78	5	167	56	1.27	9.57	5	286	56
2	0	4	1	0.030	2	8	6	0.023	0.050	2	14	6
2	0	4	1	0.030	2	8	6	0.028	0.050	2	14	6
2	0	6	4	0.432	4	25	15	0.091	*	8	152	45
2	3	2	3	0.045	2	14	6	0.035	0.053	2	14	6
1	2	4	1	0.023	2	4	3	0.022	0.042	2	4	3
2	5	4	1	0.060	2	13	6	0.03	0.077	2	14	6
2	6	4	1	0.20	4	44	15	0.12	0.29	4	44	15
5	11	2	1	7.60	3	461	56	4.45	12.23	3	461	56
6	13	2	1	1.00	2	209	26	0.40	1.29	2	209	26
6	15	2	1	1.01	2	209	26	0.42	1.48	2	209	26
10	11	2	1	12.3	2	714	44	1.83	16.76	2	1000	55
10	25	2	1	28.60	2	1000	66	5.92	43.68	2	1000	66
10	31	2	1	29.70	2	1000	66	12.50	44.29	2	1000	66
13	35	2	1	383.97	2	2379	78	32.41	417.96	2	2379	78
15	16	2	1	674.534	2	3059	120	40.35	780.371	2	3875	136
20	30	2	1	33219.9	2	10625	231	1117.33	35310.7	2	10625	231
24	58	2	1	3929.23	2	3875	136	311.94	>14h	2	20475	325

Experimentations on a 2.4 Ghz Intel core i5 processor based laptop with 3.8 GBytes memory.

Applications: Best 1-rank tensor approximation

Given a tensor $\mathcal{F} = (\mathcal{F}_{i_1, \dots, i_m})_{1 \leq i_1 \leq n_1, \dots, 1 \leq i_m \leq n_m} \in \mathbb{R}^{n_1 \times n_2 \cdots \times n_m}$

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$$\begin{aligned} & \max_{x^1 \in \mathbb{R}^{n_1}, \dots, x^m \in \mathbb{R}^{n_m}} |F(x^1, \dots, x^m)| \\ & \text{s.t. } \|x^1\| = \dots = \|x^m\| = 1 \end{aligned}$$

where $F(x^1, \dots, x^m) = \sum_{1 \leq i_1 \leq n_1, \dots, 1 \leq i_m \leq n_m} \mathcal{F}_{i_1, \dots, i_m} \cdot (x^1)_{i_1} \cdots (x^m)_{i_m}$

Example Best 1-rank symmetric tensor approximation

$\mathcal{F} \in S^3(\mathbb{R}^3)$ with entries

$\mathcal{F}_{111} = 0.0517, \mathcal{F}_{112} = 0.3579, \mathcal{F}_{113} = 0.5298, \mathcal{F}_{122} = 0.7544, \mathcal{F}_{123} = 0.2156,$
 $\mathcal{F}_{133} = 0.3612, \mathcal{F}_{222} = 0.3943, \mathcal{F}_{223} = 0.0146, \mathcal{F}_{233} = 0.6718, \mathcal{F}_{333} = 0.9723.$

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$$F(x_0, x_1, x_2) = 0.0517x_0^3 + 0.3579x_0^2x_1 + 0.5298x_0^2x_2 + 0.7544x_0x_1^2 + 0.2156x_0x_1x_2 + \\ 0.3612x_0x_2^2 + 0.3943x_1^3 + 0.0146x_1^2x_2 + 0.6718x_1x_2^2 + 0.9723x_2^3;$$

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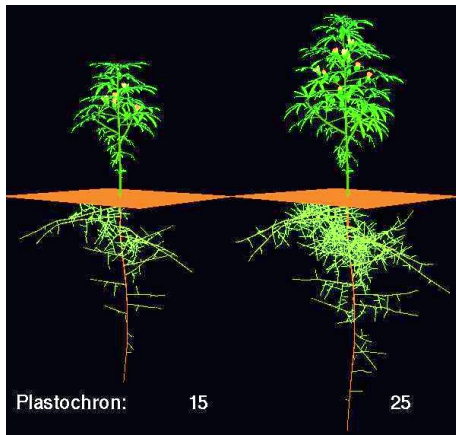
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Solution: the rank-1 tensor $\lambda \cdot u^{\otimes 3}$ with $\lambda = 1.093$, $u = (-0.203893, -0.248661, -0.946887)$
 $\|\mathcal{F} - \lambda \cdot u^{\otimes 3}\|^2 = 1.515159281.$

Applications: Root system model-Stochastic model

- 14 parameters (only 4 estimated on images).
- 15 statistics (size, shape, ...)



How use our algorithm in this root system model?

- Objective: study which statistics are important.
- Minimize quadratic problem in 15 variables (statistics) where its sum is equal to 1 and all of them are non-negatives
- Solution: The variables which are zero correspond to statistics which are not important.

THANK YOU FOR YOUR ATTENTION!!!