Modélisation compositionnelle d'architectures GALS dans un modèle de calcul polychrone

(Compositional modeling of GALS architecture in a polychronous model of computation)

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Embedded systems

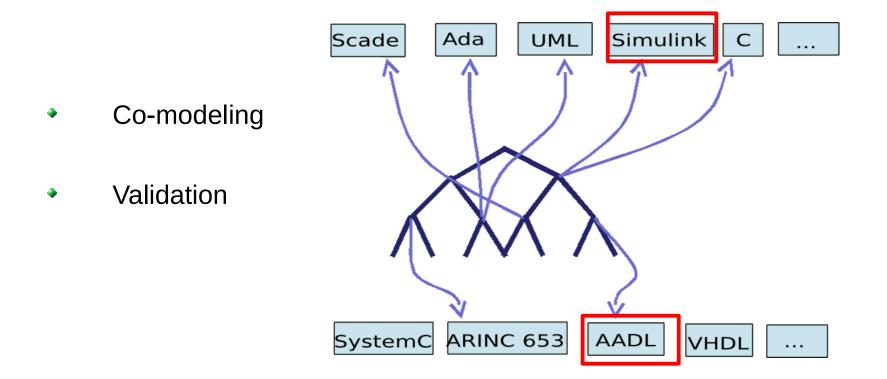
Application domains

Avionics, automobile, telecommunications, ...

Embedded systems design

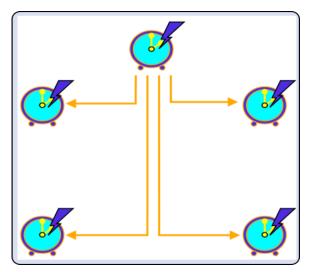
- Design methodology
 Modular design
 System level co-design
 GALS
- Modeling & design language
 UML, AADL, SystemC, ...
- Connecting Sreen Phore Mobile Phore Mobile Phore Set Bor Auto PC Auto PC Data Chent This Chent Mellow Mellow
- Problems: determinism, property verification, ...

Motivation (1)



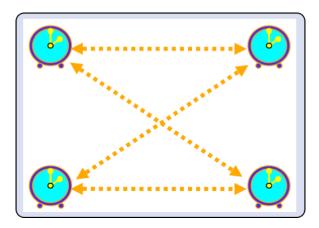
Motivation (2)

- Synchronous models of computation
- Master clock
- Lustre, Simulink, ...



Asynchronous models of computation

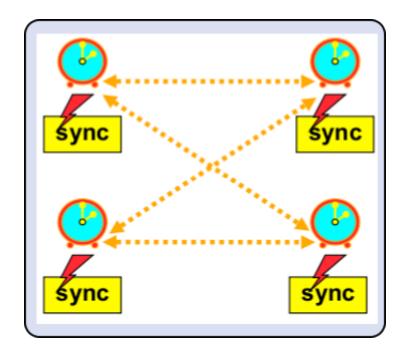
- No global clock
- UML, SysML, ...



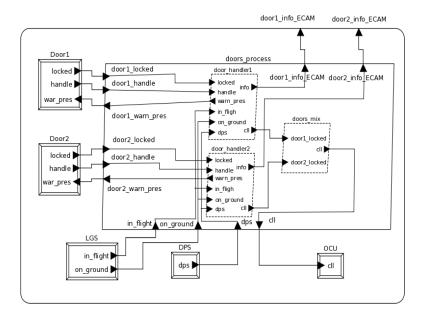
Motivation (3)

Polychronous model of computation

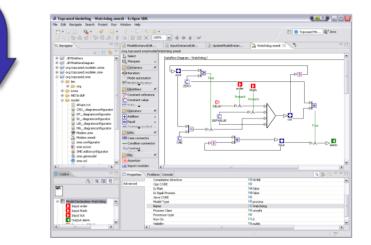
- Composing modules
- Each module is a synchronous software
- No master clock
- Clocks are related to synchronization constraints



Proposition of this work



Modeling



Simulation & validation



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Outline

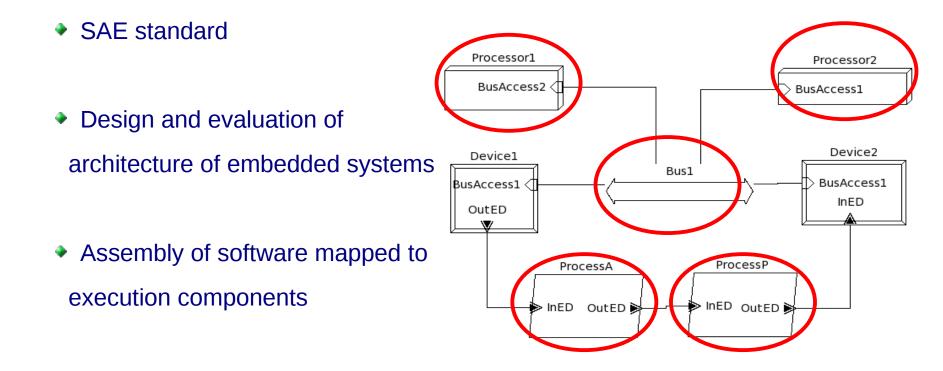
Context

AADL specification

Signal language and Polychrony

- Contributions
- Case study
- Perspectives and conclusions

Architecture Analysis and Design Language



AADL

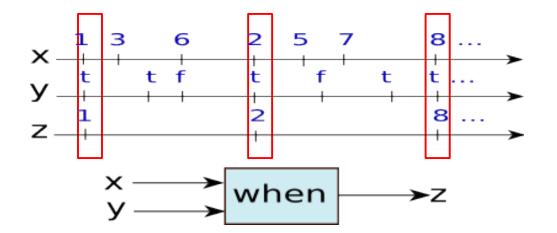
Component-based architecture

- Application software
- Execution platform
- Composite

A data	<pre>improcessor improcessor i</pre>
composite	

Signal – a multi-clocked data-flow language

- Formal specification of embedded real-time systems
- Model of computation suitable for GALS
- Polychronous model of computation: multi-clocked



Outline

- Context
- Contribution

Modeling AADL components in Signal

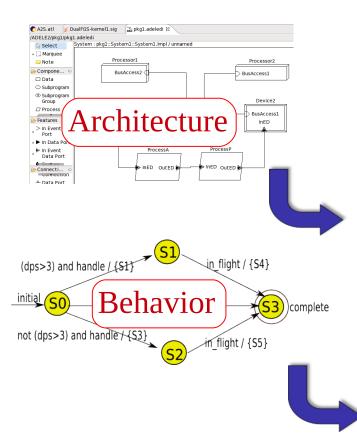
Distributed model generation

- Case study
- Perspectives and conclusions

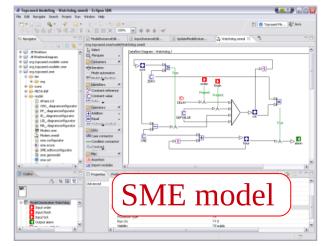
Proposed approach

Modeling AADL in Signal

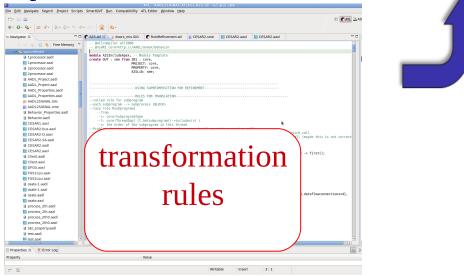
- Architecture components
- Behavior specifications (Behavior Annex, Simulink ...)



Polychrony



TopCased



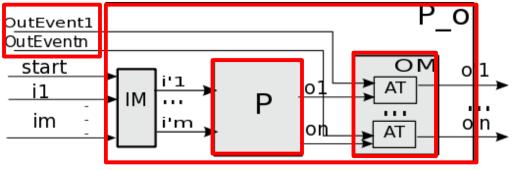
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From abstract logical time to more concrete simulation time (1)

Modeling computation latencies

- Synchronous program: logical instantaneous execution
- AADL model: computation for a specified time interval
- Adapter: interface different timing semantics
 - P: process
 - P_o: container

OM: (output) "memory" process

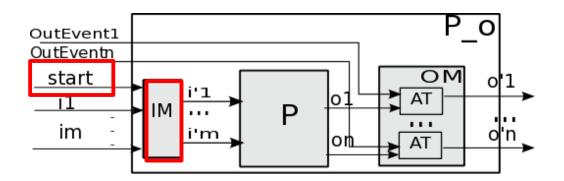


From abstract logical time to more concrete simulation time (2)

Modeling propagation delays

- Synchronous program: instantaneous communication
- AADL model: received input could be memorized
- Activation signal

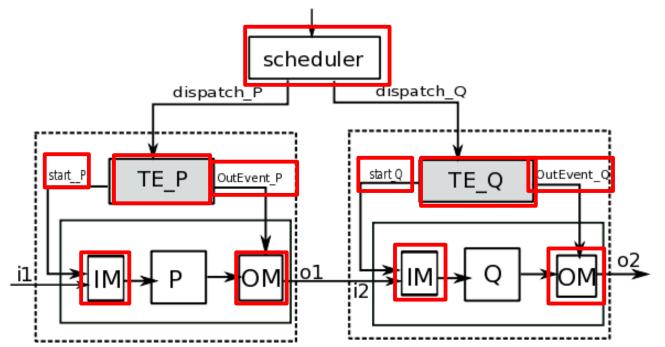
IM: (input) "memory" process



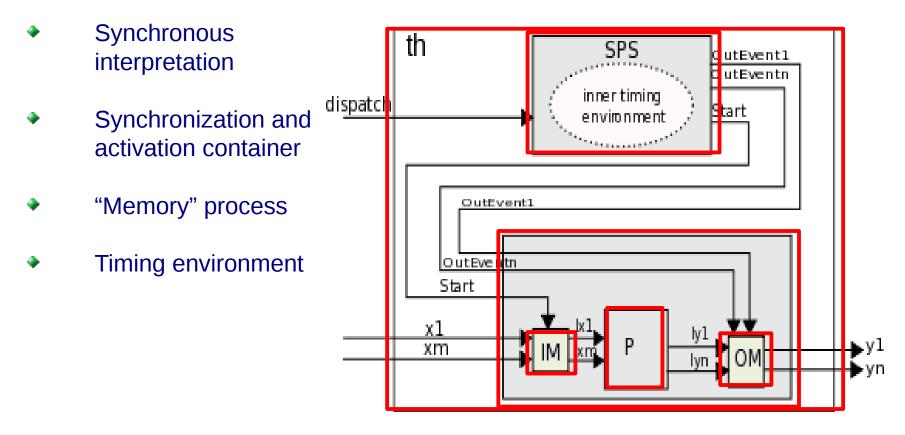
From abstract logical time to more concrete simulation time (3)

Towards modeling time-based scheduling

- How to control the activation and delay conditions
- How to generate these conditions
- Timing environment

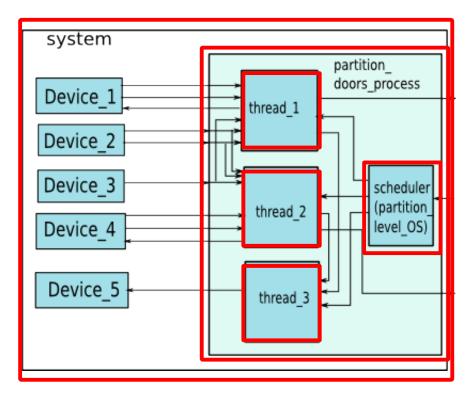


Thread modeling



Components implemented in this work

- Software
 Thread
 Process
 Subprogram
 Data
- Hardware
 Processor
 Bus
 Device
- System



Outline

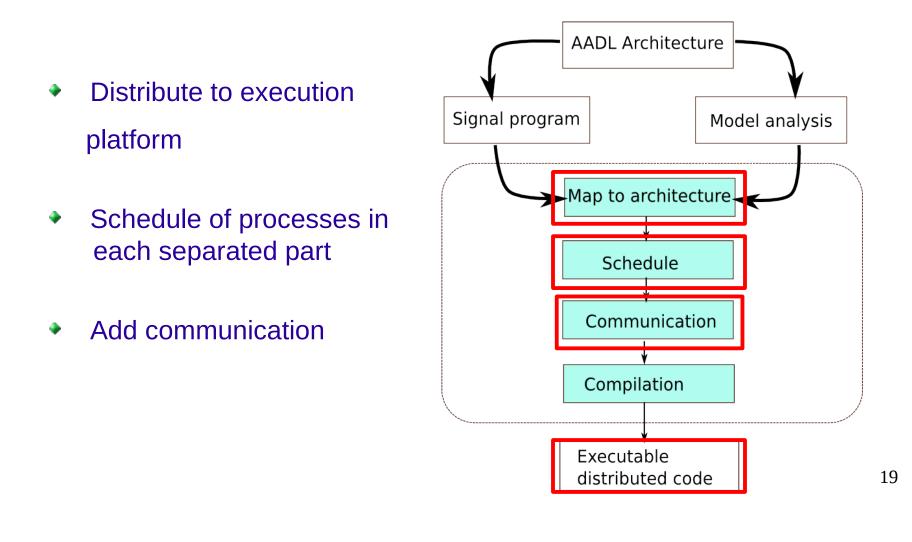
- Context
- Contribution

Modeling AADL components in Signal

Distributed model generation

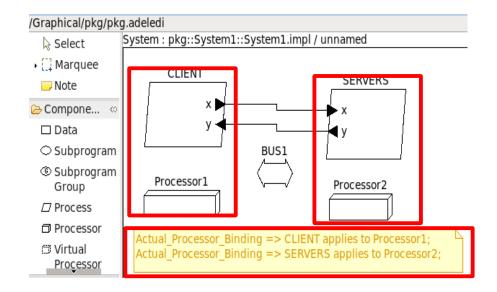
- Case study
- Perspectives and conclusions

Virtual prototyping of distributed code generation

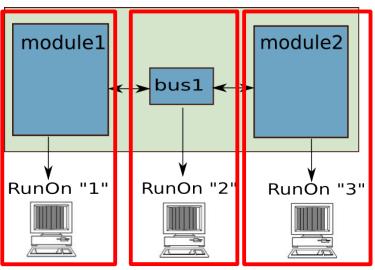


A distribution example

- Distribution properties
- Assign each module to a different processor
- Scheduling



Communication



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Outline

Context

Contribution

Modeling AADL components in Signal

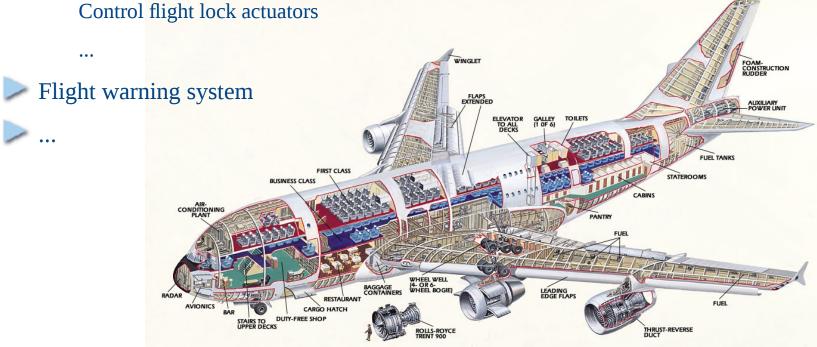
Distributed model generation

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A350 Doors Management System

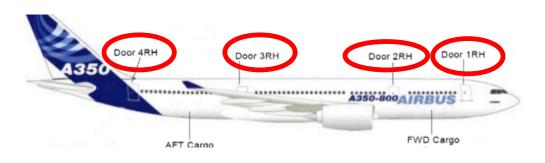
Flight control systems

- Landing gear system
- **Doors management system**
 - Passenger doors, emergency exits, cargo doors
 - Monitor doors status via door sensors



Simplified Doors and Slides Control System

 Software component monitor door status control flight lock

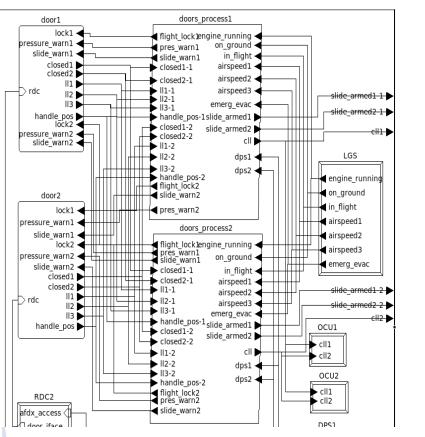


Core Processing Remote Data Hardware equipments Input/Output Modules **Concentrators** (CPIOM) (RDC) Door actuators Aircraft Full Duplex (AFDX) Door sensors AFDX bus Overflow Differential Landing gear door. door Valve Control pressure system (LGS) sensors actuators Unit (OCU) system (DPS)

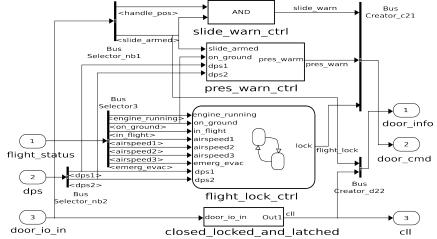
Co-modeling

Simulink

AADL

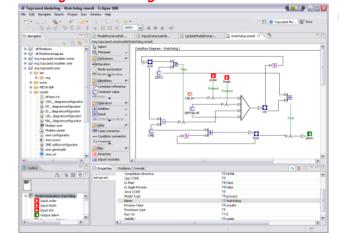


Asynchronous structural specification



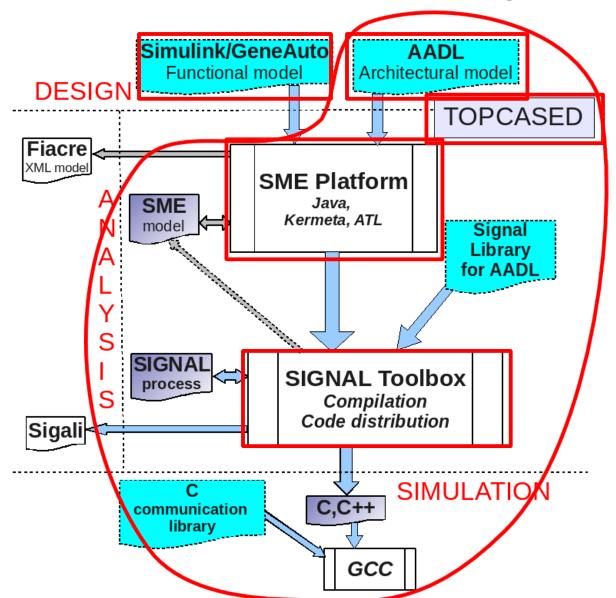
Synchronous functional specification

Polychrony



GALS simulation model

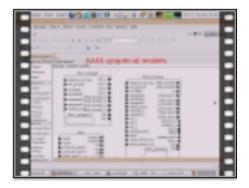
Global view of co-design

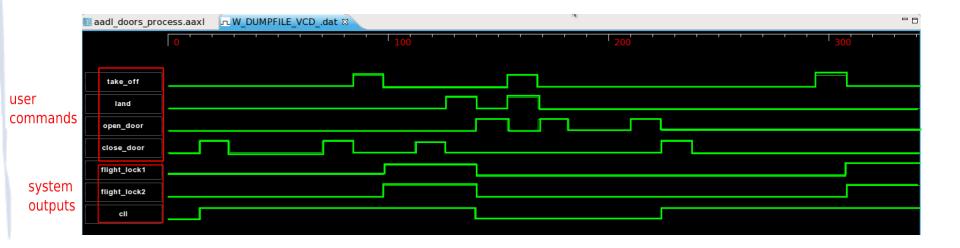


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Simulation

- System modeling
- Formal transformation
- System composition
- VCD-based simulation





Conclusions and perspectives

Conclusions

Polychronous modeling of a subset of AADL model

- Formal interpretation of AADL components
- An effective method for modeling and validation of GALS architecture

Distributed code generation

Distribute code to different processors

Formal verification, simulation and analysis

A case study for co-modeling and simu

Perspectives

Extension of the modeling

- Cover a larger subset of AADL
- Dynamic scheduling model and schedulability analysis

Extension of validation

Test case generation



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