

Automatic Selection of Sequence Transformations

By J. P. Delahaye

Abstract. Some methods of automatic selection of sequence transformations for accelerating the convergence of sequences are presented. Two theorems show the efficiency of these methods. This is confirmed by numerical experiments.

Introduction. When faced with the great number of various methods for accelerating the convergence of sequences [3], [4], [5], and also with the problem of the choice of parameters for some of them (Richardson process [8], ρ -algorithm [2]), the user is in a quite difficult position. If some precise information about the behavior of the sequence to be accelerated is known, it is possible to determine the most powerful acceleration method, but, even in this case, several possibilities remain. The user can (if he has plenty of time!) try all the methods and choose the best one with the help of some test problems.

In practice, however, it happens very often that the choice is arbitrary and thus is not the best one for the problem.

In this paper some automatic processes for selecting a good method of acceleration among several sequence transformations are proposed. All these processes work with the following scheme:

At the n th step the various transformations "in competition", A_1, A_2, \dots, A_k , are applied to the sequence (S_n) of a metric space E . The transformed points $A_1^{(n)}, A_2^{(n)}, \dots, A_k^{(n)}$ are obtained. Then, one of the transformed points $A_1^{(n)}, A_2^{(n)}, \dots, A_k^{(n)}$ is selected by using various tests (several are defined and studied). This point must be the best one at this step.

The use of these automatic selection methods is more expensive than the use of a single transformation for accelerating the convergence because it is necessary to use, simultaneously, several transformations. However, this is not a drawback because acceleration transformations are generally not expensive.

In the first section we present various general methods for selection, and we give some examples. In the second section we prove two theorems which legitimize the proposed methods. The numerical results of the third section confirm the practical efficiency of these methods.

1. General Definitions for Selection Methods.

1.1. *Count Coefficients.* Let $\mathcal{R}_i^{(n)}$ be a relation (true or false depending on i and n) defined for all $i \in \{1, 2, \dots, k\}$ and for all $n \in \mathbb{N}, n \geq n_0$.

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Let us set the following count coefficients:

$$\begin{aligned}
 {}^0r_i^{(n)} &= \begin{cases} 0 & \text{if } n < n_0 \text{ or if } \mathfrak{R}_i^{(n)} \text{ is not true,} \\ 1 & \text{if } n \geq n_0 \text{ and if } \mathfrak{R}_i^{(n)} \text{ is true,} \end{cases} \\
 {}^1r_i^{(n)} &= \text{card}\{q \in \{0, 1, \dots, n\} | n \geq n_0 \text{ and } \mathfrak{R}_i^{(n)} \text{ is true}\}, \\
 {}^2r_i^{(n)} &= \begin{cases} 0 & \text{if } n < n_0 \text{ or if } \mathfrak{R}_i^{(n)} \text{ is not true,} \\ \max\{q \in \{1, 2, \dots, n - n_0 + 1\} | \\ \mathfrak{R}_i^{(n)}, \mathfrak{R}_i^{(n-1)}, \dots, \mathfrak{R}_i^{(n-q+1)} \text{ are true}\}, & \text{if } n \geq n_0 \text{ and if } \mathfrak{R}_i^{(n)} \text{ is true.} \end{cases}
 \end{aligned}$$

Note that, even if $\mathfrak{R}_i^{(n)}$ is not defined, the count coefficients exist when $n < n_0$ and become zero. We have the following properties:

$$\forall i \in \{1, 2, \dots, k\}, \forall n \in \mathbb{N}:$$

$${}^1r_i^{(n)} = \sum_{j=0}^n {}^0r_i^{(j)}; \quad 0 < {}^0r_i^{(n)} < {}^2r_i^{(n)} < {}^1r_i^{(n)}; \quad n \geq n_0 \Rightarrow {}^1r_i^{(n)} < n - n_0 + 1.$$

It is possible to define other count coefficients. For example, a coefficient can be defined such that $\mathfrak{R}_i^{(n)}$ has more importance than $\mathfrak{R}_i^{(n-1)}$, $\mathfrak{R}_i^{(n-1)}$ has more importance than $\mathfrak{R}_i^{(n-2)}$ etc. Let A_1, A_2, \dots, A_k be k sequence transformations. We denote by $A_1^{(n)}(S_m), A_2^{(n)}(S_m), \dots, A_k^{(n)}(S_m)$, respectively, the sequences obtained by applying these transformations to the sequence (S_m) . For convenience, we shall also write $A_i^{(n)}$ instead of $A_i^{(n)}(S_m)$. All the sequences in this paper are sequences of a metric space (E, d) . If we substitute the relation $\mathfrak{R}_i^{(n)}$ for the relation $(\mathcal{C}_i^{(n)})$: $A_i^{(n)} = A_i^{(n-1)}$ (which is defined only if $n > 1$), we obtain other count coefficients denoted by ${}^0c_i^{(n)}, {}^1c_i^{(n)}, {}^2c_i^{(n)}$.

Let $l \in \mathbb{N}$. If we substitute the relation $\mathfrak{R}_i^{(n)}$ for the relation

$$({}_l\mathcal{D}_i^{(n)}): \max_{0 < q < l} d(A_i^{n-q}, A_i^{n-q-1}) = \min_{1 < j < k} \max_{0 < q < l} d(A_j^{n-q}, A_j^{n-q-1})$$

(which is defined only if $n \geq l + 1$), we obtain other count coefficients denoted by ${}^0d_i^{(n)}, {}^1d_i^{(n)}, {}^2d_i^{(n)}$. When $l = 0$, we denote by $\mathcal{D}_i^{(n)}$ the relation ${}_l\mathcal{D}_i^{(n)}$ and by ${}^0d_i^{(n)}, {}^1d_i^{(n)}, {}^2d_i^{(n)}$ the associated count coefficients.

Remark. The theorems proved in the following sections concern only the relations $\mathcal{C}_i^{(n)}$ and ${}_l\mathcal{D}_i^{(n)}$. However, it is possible to define other relations.

In particular, for methods based on interpolation (Richardson process [8], ρ -algorithm [4], etc.), we can use the relation

$$d(S_n, S_n^j) = \min_{1 < j < k} d(S_n, S_n^j),$$

where S_n^j is the value at x_n^j of the interpolation function which takes the values $S_{n-k}, S_{n-k+1}, \dots, S_{n-1}$ at $x_{n-k}^j, x_{n-k+1}^j, \dots, x_{n-1}^j$ ($(x_n^1), (x_n^2), \dots, (x_n^k)$ are k sequences of parameters; for example, in the Richardson process it is assumed that: $\forall m, n: n \neq m \Rightarrow x_n^j \neq x_m^j$, and $\lim_{n \rightarrow \infty} x_n^j = 0$). Such methods are more expensive than the methods studied in this paper, because the calculation of S_n^j practically implies the determination of the interpolation function. However, some of the obtained results may be of interest [7].

1.2. *Selection Methods.* Let $f \in \{0, 1, 2\}$. With the help of the coefficients ${}^f r_i^{(n)}$, we define a new transformation A which selects at each step, one of the transformations A_i ($i \in \{1, 2, \dots, k\}$).

Step n of the Transformation $A = {}^fR(A_1, A_2, \dots, A_k)$. We compute $f_{r_1}^{(n)}, f_{r_2}^{(n)}, \dots, f_{r_k}^{(n)}$. Let $i(n)$ be the smallest i such that

$$f_{r_i}^{(n)} = \max_{1 < j < k} f_{r_j}^{(n)}.$$

We choose $A^{(n)} = A_{i(n)}^{(n)}$.

When applied together with the above count coefficients and k sequence transformations, this scheme defines new sequence transformations denoted by ${}^0C(A_1, A_2, \dots, A_k), {}^1C(A_1, A_2, \dots, A_k), {}^2C(A_1, A_2, \dots, A_k), {}^0D(A_1, A_2, \dots, A_k), {}^1D(A_1, A_2, \dots, A_k), {}^2D(A_1, A_2, \dots, A_k)$. If $l = 0$, the last three transformations are denoted by ${}^0D(A_1, A_2, \dots, A_k), {}^1D(A_1, A_2, \dots, A_k), {}^2D(A_1, A_2, \dots, A_k)$.

Remark 1. Sometimes it is possible to compute recursively the count coefficients. For example, the computation of ${}^1c_i^{(n)}$ need $A_i^{(0)}, A_i^{(1)}, \dots, A_i^{(n)}$; but, in fact, it is possible to do it only with ${}^1c_i^{(n-1)}, A_i^{(n)}, A_i^{(n-1)}$, because of the obvious relations:

$$\begin{aligned} {}^1c_i^{(n)} &= {}^1c_i^{(n-1)} && \text{if } A_i^{(n)} \neq A_i^{(n-1)}, \\ {}^1c_i^{(n)} &= {}^1c_i^{(n-1)} + 1 && \text{if } A_i^{(n)} = A_i^{(n-1)}. \end{aligned}$$

Remark 2. In a selection method of sequence transformations, it is desirable to have a normalization, i.e. an eventual shift of the index such that the computation of $A_i^{(n)}$ uses, at each step, the same points of the sequence (S_n) ; for example, points among S_0, S_1, \dots, S_n . The calculation of $\varepsilon_2^{(n)}$ uses S_n, S_{n+1}, S_{n+2} [3], hence, if ε_2 is one of the sequence transformations "in competition", we write $A_i^{(0)} = S_0; A_i^{(1)} = S_1; A_i^{(n)} = \varepsilon_2^{(n-2)}$ for $n > 2$.

When this normalization is respected, the new obtained sequence transformations are also normalized.

Remark 3. It is possible, in practical cases, that one of the used transformations can no longer be applied (for example in the case of division by zero). In such a case two kinds of strategies can be employed.

When this is the case for the transformation A_j at the step n_0 :

- (1°) For all $n > n_0$, only the transformations A_i with $i \neq j$ are considered.
- (2°) For all $n > n_0$, we take

$$A_j^{(n)} = A_j^{(n_0)}; \quad \mathfrak{R}_j^{(n)} \Leftrightarrow \mathfrak{R}_j^{(n_0)}.$$

Remark 4. Methods of selection among a finite number of transformations are the only ones studied herein. However, it is possible to study the case of an infinite number of transformations. Such methods are studied in [7].

Example 1. Let A_1, A_2 be two given sequence transformations. ${}^0D(A_1, A_2)$ is the sequence transformation A which, at the step n , produces the more stable one of A_1 or A_2 ; i.e.

$$\begin{aligned} A^{(n)} &= A_1^{(n)} && \text{if } d(A_1^{(n)}, A_1^{(n-1)}) < d(A_2^{(n)}, A_2^{(n-1)}), \\ A^{(n)} &= A_2^{(n)} && \text{if } d(A_2^{(n)}, A_2^{(n-1)}) < d(A_1^{(n)}, A_1^{(n-1)}). \end{aligned}$$

${}^1C(A_1, A_2)$ is the sequence transformation A which, at the step n , produces the less frequently changed one of A_1 or A_2 ; i.e. $-A^{(n)} = A_1^{(n)}$ if in the first n steps $A_1^{(q)} = A_1^{(q-1)}$ is more frequently true than $A_2^{(q)} = A_2^{(q-1)}$; $A^{(n)} = A_2^{(n)}$ if not.

Example 2. Selection among Richardson processes [3], [4], [8]. Let (t_n) be a sequence of real numbers such that $\lim_{n \rightarrow \infty} t_n = 0$ and $i \neq j \Rightarrow t_i \neq t_j$. The

Richardson process with parameters (t_n) is the calculation of $T_k^{(n)} = P_k^{(n)}(0)$, where $P_k^{(n)}$ is the unique polynomial such that

$$\begin{cases} P_k^{(n)}(t_n) = S_n; & P_k^{(n)}(t_{n+1}) = S_{n+1}; \dots; P_k^{(n)}(t_{n+k}) = S_{n+k}, \\ d^0 P_k^{(n)} \leq k. \end{cases}$$

When k is fixed, we obtain a sequence transformation. But usually it is interesting to consider the diagonal transformation $n \rightarrow T_n^{(n)}$. For example, with three sequences of parameters $(t_n), (x_n), (y_n)$, we obtain three diagonal transformations $(T_n^{(n)}, (X_n^{(n)}, (Y_n^{(n)})$ which can be denoted by $A_1^{(n)}, A_2^{(n)}, A_3^{(n)}$. Below, we shall see that the new transformation ${}^1D(A_1, A_2, A_3)$ is an interesting one, because it “pluralizes” the extrapolation properties of A_1, A_2, A_3 . In such an example it is not necessary to “normalize” the sequence transformations A_1, A_2, A_3 because, at the step n , each of them uses the same points $S_n, S_{n+1}, \dots, S_{2n}$.

Example 3. Practically, the most interesting methods are the selections among transformations as various as possible. We shall see, in the third section, a few computational experiences with ${}^jD(A_1, A_2, A_3, A_4, A_5, A_6)$ where

- A_1 is the Richardson process [3], [8],
- A_2 is the ϵ -algorithm [3], [10], [11],
- A_3 is the ρ -algorithm [2],
- A_4 is the Overholt process [3], [9],
- A_5 is the θ -algorithm [1], [3],
- A_6 is the iterated Δ^2 [4].

2. Two Results on Selection Methods.

2.1. *Exact Transformations.* We recall a few definitions which are used below. We say that the sequence transformation A is *regular for the family* \mathfrak{S} of convergent sequences if

$$\forall (S_n) \in \mathfrak{S} : \lim_{n \rightarrow \infty} S_n = \lim_{n \rightarrow \infty} A^{(n)}.$$

We say that the sequence transformation A is *semiregular for the family* \mathfrak{S} of convergent sequences if

$$\begin{aligned} \forall (S_n) \in \mathfrak{S} & \left[\exists n_0 \in \mathbf{N}, \forall n > n_0 A^{(n)} = A^{(n+1)} \right] \\ & \Rightarrow \left[\exists m_0 \in \mathbf{N}, \forall m > m_0 A^{(m)} = \lim_{n \rightarrow \infty} S_n \right]. \end{aligned}$$

We say that the sequence transformation A is *exact for the family* \mathfrak{S} of convergent sequences if

$$\forall (S_n) \in \mathfrak{S}, \exists m_0 \in \mathbf{N}, \forall m > m_0 : A^{(m)} = \lim_{n \rightarrow \infty} S_n.$$

We have

$$[A \text{ exact}] \Rightarrow [A \text{ regular}] \Rightarrow [A \text{ semiregular}].$$

Results concerning these properties are known for most of the acceleration methods ([3], [4], [6], etc.).

THEOREM 1. *Let $\mathfrak{S}_1, \mathfrak{S}_2, \dots, \mathfrak{S}_k$ be k families of convergent sequences. For each $i \in \{1, 2, \dots, k\}$, let A_i be a sequence transformation, exact for \mathfrak{S}_i and semiregular for $\mathfrak{S}_1 \cup \mathfrak{S}_2 \cup \dots \cup \mathfrak{S}_k$. Then the transformations ${}^1C(A_1, A_2, \dots, A_k), {}^2C(A_1, A_2, \dots, A_k), {}^1D(A_1, A_2, \dots, A_k), {}^2D(A_1, A_2, \dots, A_k)$ are exact for $\mathfrak{S}_1 \cup \mathfrak{S}_2 \cup \dots \cup \mathfrak{S}_k$.*

Proof. We indicate a proof only for ${}^1C(A_1, A_2, \dots, A_k)$ denoted by A . One can easily adapt this proof to the other cases.

Let $(S_m) \in \mathfrak{S}_1 \cup \mathfrak{S}_2 \cup \dots \cup \mathfrak{S}_k$. Let I_0 be the set of integers i_0 such that A_{i_0} is exact for (S_m) . From the assumptions there is at least one element in I_0 , but it is possible that there are several ones (because we have not supposed that the \mathfrak{S}_i are disjoint). Since I_0 is finite, there exists $p_0 \in \mathbb{N}$ such that

$$\forall i_0 \in I_0, \forall p \geq p_0: A_{i_0}^{(p)} = S \quad (S = \lim_{m \rightarrow \infty} S_m).$$

Hence, for each $p \geq p_0, i_0 \in I_0$, we have

$$(*) \quad {}^1c_{i_0}^{(p)} \geq p - p_0.$$

Contrarily, if $i \notin I_0$, there exists an infinite set of integers p such that

$$A_i^{(p)} \neq A_i^{(p-1)}$$

(this, from the assumption that A is semiregular). Consequently, there exists an integer $p_1 \geq p_0$ such that, for each $i \notin I_0, p \geq p_1$,

$$(**) \quad {}^1c_i^{(p)} < p - p_0.$$

From (*), (**) we obtain that, for every $p \geq p_1, i(p) \in I_0$, and then $A^{(p)} = S$.

Remark 1. Theorem 1 tells nothing about the selection methods 0C and 0D , and it is possible, by counterexamples, to prove that generally the theorem is not true for 0C and 0D .

Remark 2. The integer p_1 in the proof cannot be determined without other assumptions; but in practice p_1 is close to the index p such that there exists $i: A_i^{(p)} = S$.

Remark 3. Negative results concerning sequence transformations for accelerating the convergence show that the assumptions of semiregularity are essential [7]; without similar assumptions, no theorem such as Theorem 1 is possible.

2.2 Transformations for Accelerating the Convergence. We assume, in this section, that all sequences (S_n) are convergent and verify

$$\exists n_0 \in \mathbb{N}, \forall n \geq n_0: S_n \neq \lim_{m \rightarrow \infty} S_m \text{ and } S_n \neq S_{n+1}.$$

We say that the sequence transformation A accelerates the convergence of (S_n) (resp. Δ -accelerates) if

$$\lim_{n \rightarrow \infty} d(A^{(n)}, \lim_{m \rightarrow \infty} S_m) / d(S_n, \lim_{m \rightarrow \infty} S_m) = 0$$

(respectively $\lim_{n \rightarrow \infty} d(A^{(n+1)}, A^{(n)}) / d(S_{n+1}, S_n) = 0$). When A accelerates (resp. Δ -accelerates) all the sequences (S_n) of the family \mathfrak{S} , we say that A accelerates \mathfrak{S} (resp. Δ -accelerates \mathfrak{S}). We say that the sequence transformation A is fair for \mathfrak{S} if, for every sequence $(S_n) \in \mathfrak{S}$,

(F_1) either A accelerates and Δ -accelerates (S_n) ,

(F_2) or $\exists \varepsilon > 0, \exists n_0 \in \mathbb{N}, \forall n \geq n_0, d(A^{(n+1)}, A^{(n)}) / d(S_{n+1}, S_n) > \varepsilon$.

When $E = \mathbb{R}$, a sufficient condition such that A be fair for \mathfrak{S} is: all the sequences in \mathfrak{S} are monotonic, and the sequence $(d(A^{(n+1)}, A^{(n)}) / d(S_{n+1}, S_n))$ is always convergent to some limit l . The reason is that either $l = 0$ and then A accelerates and Δ -accelerates (see [3]) or $l > 0$ and then (F_2) holds.

THEOREM 2. *Let $l \in \mathbb{N}$. Let A_1, A_2, \dots, A_k be k sequence transformations. For each $i \in \{1, 2, \dots, k\}$, we assume that A_i accelerates and Δ -accelerates \mathfrak{S}_i , a family of convergent sequences, and that A_i is fair for $\mathfrak{S}_1 \cup \mathfrak{S}_2 \cup \dots \cup \mathfrak{S}_k$. Then the transformations ${}^0D(A_1, A_2, \dots, A_k)$, ${}^1D(A_1, A_2, \dots, A_k)$, ${}^2D(A_1, A_2, \dots, A_k)$ accelerate $\mathfrak{S}_1 \cup \mathfrak{S}_2 \cup \dots \cup \mathfrak{S}_k$.*

LEMMA. *Let (S_n) be a convergent sequence with limit S . Let $(A_1^{(n)})$, $(A_2^{(n)})$, \dots , $(A_k^{(n)})$ be k sequences which accelerate the convergence of (S_n) . Let $i: \mathbb{N} \rightarrow \{1, 2, \dots, k\}$. Then the sequence $(A_{i(n)}^{(n)})$ accelerates the convergence of (S_n) .*

Proof. Let $\varepsilon \in \mathbb{R}^{+*}$. For each $i \in \{1, 2, \dots, k\}$, there is $m_i \in \mathbb{N}$ such that $\forall m \geq m_i: d(A_i^{(m)}, S)/d(S_m, S) < \varepsilon$. Letting $M = \max\{m_i | i \in \{1, 2, \dots, k\}\}$, we obtain

$$\forall m \geq M: d(A_{i(m)}^{(m)}, S)/d(S_m, S) < \varepsilon.$$

Remark. The lemma is not true with Δ -acceleration. Here is a counterexample: $S_n = 1/n$, $A_1^{(n)} = 1/n^2$, $A_2^{(n)} = 1/2n^2$, $i(n) = (3 + (-1)^n)/2$. We have

$$\begin{aligned} \lim_{n \rightarrow \infty} d(A_1^{(n+1)}, A_1^{(n)})/d(S_{n+1}, S_n) &= 0, \\ \lim_{n \rightarrow \infty} d(A_2^{(n+1)}, A_2^{(n)})/d(S_{n+1}, S_n) &= 0, \\ \lim_{n \rightarrow \infty} d(A_{i(n+1)}^{(n+1)}, A_{i(n)}^{(n)})/d(S_{n+1}, S_n) &= 1/2. \end{aligned}$$

Proof of Theorem 2. We indicate a proof only for ${}^0D(A_1, A_2, \dots, A_k)$ denoted by A . One can easily adapt this proof for the other cases. Let $(S_n) \in \mathfrak{S}_1 \cup \mathfrak{S}_2 \cup \dots \cup \mathfrak{S}_k$. Let S be its limit. Let I_0 be the set of integers $i \in \{1, 2, \dots, k\}$ such that A_i accelerates and Δ -accelerates (S_n) . From the assumptions I_0 is nonempty. If $j \notin I_0$, there exists $\varepsilon_j \in \mathbb{R}^{+*}$ and $n_j \in \mathbb{N}$ such that

$$\forall n \geq n_j, d(A_j^{(n+1)}, A_j^{(n)})/d(S_{n+1}, S_n) \geq \varepsilon_j.$$

We write $\varepsilon = \min\{\varepsilon_j | j \notin I_0\}$, $N = \max\{n_j | j \notin I_0\}$; we obtain

$$\forall n \geq N, \forall j \notin I_0: d(A_j^{(n+1)}, A_j^{(n)})/d(S_{n+1}, S_n) \geq \varepsilon.$$

Similarly there exists $N' \geq N$ such that

$$\forall n \geq N', \forall i \in I_0: d(A_i^{(N+1)}, A_i^{(n)})/d(S_{n+1}, S_n) < \varepsilon.$$

This implies that, for each $n \geq N' + l$, $i(n) \in I_0$. From the lemma we can conclude

$$\lim_{n \rightarrow \infty} d(A_{i(n)}^{(n)}, S)/d(S_n, S) = 0.$$

Remark 1. The assumptions of Theorem 2 are often satisfied in practice, but generally it is difficult to show that they are satisfied for specified transformations A_i and large \mathfrak{S}_i . Nevertheless, this theorem justifies and explains the efficiency of the selection methods ${}_lD$ as we shall see in the practical cases of Section 3.

Remark 2. We can generalize the notion of fair transformations; we say that the sequence transformation A is h -fair ($h \in \mathbb{N}$) for \mathfrak{S} if, for every sequence $(S_n) \in \mathfrak{S}$, $({}_hF_1)$ either A accelerates and Δ -accelerates (S_n) , $({}_hF_2)$ or

$$\exists \varepsilon > 0, \exists n_0 \in \mathbb{N} \forall n \geq n_0 \max_{0 < r < h} d(A^{(n-r+1)}, A^{(n-r)})/d(S_{n+1}, S_n) > \varepsilon.$$

We obtain $[A \text{ fair}] \Leftrightarrow [A \text{ 0-fair}]$. If $h > h'$, $[A \text{ h'-fair}] \Rightarrow [A \text{ h-fair}]$. The assumption "A h-fair" is more often true than the assumption "A fair". However, Theorem 2 with $l > h$ is still true.

3. Computational Experiences. The computational experiences presented here were made with C. Brezinski's codes [4], and I would like to take this opportunity to thank him, for his excellent advice and support.

Example 1. In Table 1 we present the first 10 steps for the δ transformations in competition (see Section 1, Example 3) when they are applied to the sequence

$$S_n = \frac{1}{2} \left(\frac{1}{2} \right)^2 + \frac{1}{4} \left(\frac{1 \cdot 3}{2 \cdot 4} \right)^2 + \dots + \frac{1}{2n} \left(\frac{1 \cdot 3 \cdot \dots \cdot (2n-1)}{2 \cdot 4 \cdot \dots \cdot (2n)} \right)^2 \rightarrow .22005074 \dots$$

The selected transformation by the method 0D at the n th step is indicated with an X. We see that this chosen transformation is always among the transformations R , ρ , or θ , which are here the transformations which accelerate the convergence. Consequently, we can say that the choice is correct. The method 1D is also correct; at the step n with $n > 3$, the chosen transformation is always the ρ -algorithm. The method 2D gives exactly the same results that the method 0D .

TABLE 1

S_n	$R(1/n)$	ϵ	$\rho(n)$	Ov.	θ	Δ^2 it.
.125	.125 1	.125 1	.125 1	.125 1	.125 1	.125 1
.16015625	.19531250 1	.16015625 2	.16015625 2	.16015625 2	.16015625 2	.16015625 2
.17643229	.21582031 2	.19046336 3	.22077047 1	.19046336 5	.17643229 6	.19046336 3
.18577830	.21959093 2	.19838255 5	.22033281 (1)	.20227823 4	.21918327 3	.19838255 5
.19183451	.22002856 2	.20570155 6	.22004511 (1)	.20782237 5	.21966574 3	.20936274 4
.19607526	.22005258 2	.20871905 6	.22004902 (1)	.21095162 5	.21984779 3	.21158726 4
.19920946	.22005113 (3)	.21158833 6	.22005079 2	.21293141 5	.22005077 1	.21590176 4
.20161980	.22005076 1	.21305538 6	.22005076 1	.21428050 5	.22005078 (3)	.21659597 4
.20353087	.22005074 1	.21447121 6	.22005074 (1)	.21524960 5	.22005077 3	.21839937 4
.20508314	.22005074 1	.21529441 6	.22005074 (1)	.21597391 5	.22005078 3	.21861073 4

Since we know that $S = .22005074$, we can determine, at each step, the exact rank of each transformation (this rank is indicated in Table 1 by a number under each transformed point). For example at step 4 (the first significant one) the ρ -algorithm gives .22033281 and this is the best transformed point; the rank of the ρ -algorithm at step 4 is consequently 1. The method 0D chooses the ρ -algorithm at step 4; this is the best possible choice. At steps 5 and 6 the choice is still the best possible, but at

step 7^0D chooses the Richardson process whose rank is 3. The rank sequence of chosen transformations is (1, 1, 1, 3, 3, 1, 1). This is not the best possible rank sequence, which is (1, 1, 1, 1, 1, 1, 1). However, it is a good rank sequence because all ranks are < 3 , and there are only three sequence transformations accelerating the convergence of (S_n) . For the two following examples, we have only indicated the rank sequence of the chosen transformation when the method 0D is applied.

Example 2. $S_n = \exp(-\sqrt{n} / 10\sqrt{2}) / n$.

TABLE 2

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
			2	1	1	3	3	1	1	1	1	1	2	2	3	3	3	3	3	3	3	3	2	2
25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49
3	3	2	3	3	1	1	1	4	2	3	3	2	1	3	1	2	2	2	2	1	2	2	2	2

Only three transformations accelerate (S_n) : ϵ -algorithm, ρ -algorithm, and Δ^2 iterated. When n is large enough, at each step n , 0D chooses one of these three transformations.

Example 3. $S_{2n} = (1/2n)$, $S_{2n+1} = (4n + 5)/(2n + 2)^2$.

TABLE 3

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
			5	2	2	2	3	3	4	4	3	3	3	3	3	3	3	3	4	3	2	3	2	3
25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49
2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2

Only two transformations accelerate (S_n) : ϵ -algorithm and ρ -algorithm. The best one (ϵ -alg.) is not chosen because the transformed sequence is alternating; when n is large enough, the choice at the step n is the ρ -algorithm.

Université des Sciences et Techniques de Lille
 I UER D'IEEA
 59655 Villeneuve D'Ascq Cedex, France

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